On the consistency of the MLE for observation-driven models

Paolo Gorgi

Joint work with:

F. Blasques

S. J. Koopman



Outline



- 1 Motivation
- 2 Main results
- 3 Empirical illustrations
- 4 References

Introduction



- In observation-driven models invertibility is needed to
 - 1) Ensure the consistency of the MLE.
 - 2) Uncover the true path of the time varying parameter (even if θ_0 is known).
- Problem: existing conditions for invertibility are often useless in practice. In particular, to ensure invertibility to hold we need to impose severe restrictions that are unreasonable in empirical applications.
- **Solution:** we derive the consistency of the MLE considering feasible invertibility conditions that can cover situations of practical interest.

Motivation: the model



 Consider the Beta-t-GARCH model with leverage effects of Creal et al. (2013) and Harvey (2013)

$$y_t = \sqrt{f_t} \varepsilon_t, \quad \varepsilon_t \sim t_v(0, 1),$$

$$f_{t+1} = \omega + \beta f_t + (\alpha + \gamma d_t) \frac{(v+1)y_t^2}{(v-2) + f_t^{-1}y_t^2},$$

where $d_t = 1$ if $y_t \le 0$ and $d_t = 0$ otherwise.

lacktriangle To ensure the consistency of the MLE, the parameter region Θ where the likelihood is maximized has to satisfy

$$E \log \left| \beta + (\alpha + \gamma d_t) \frac{(\nu + 1)y_t^4}{((\nu - 2)\bar{\omega} + y_t^2)^2} \right| < 0, \quad \forall \ \theta \in \Theta,$$

and $\theta_0 \in \Theta$.

Motivation: the parameter region



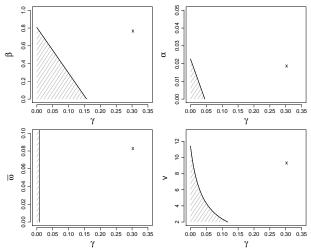


Figure: Parameter region where we can ensure that the invertibility condition hold. The cross denotes the parameter estimate using monthly log-differences of the S&P 500 stock index.

Observation-driven models



■ We observe data $\{y_t\}_{t=1}^n$, and we consider the following model

$$y_t|f_t \sim p(y_t|f_t, \theta),$$

 $f_{t+1} = \phi(f_t, y_t, \theta), \ t \in \mathbb{Z},$

where $p(\cdot|f_t;\theta)$ is a density function, $\theta \in \Theta$ a parameter vector and ϕ is a continuous function.

- Under the assumption of correct specification, the data generating process (DGP) satisfies the model equations at $\theta = \theta_0$ and f_t^o denotes the true time varying parameter.
- We are interested in ML estimation of the static parameter θ and, in particular, the consistency of the MLE.

The likelihood function



■ Using the observed data, the **filtered parameter** is obtained as

$$\hat{f}_{t+1}(\theta) = \phi(\hat{f}_t(\theta), y_t, \theta), \quad t \in \mathbb{N},$$

for an **initial value** $\hat{f}_1(\theta) \in \mathcal{F}_{\theta} \subseteq \mathbb{R}$.

■ The MLE is then obtained maximizing the likelihood

$$\hat{L}_n(\theta) = n^{-1} \sum_{t=1}^n \log p(y_t | \hat{f}_t(\theta), \theta),$$

over the parameter set Θ .

■ The stability (**invertibility**) of $\{\hat{f}_t(\theta)\}_{t\in\mathbb{N}}$ for the $\theta\in\Theta$ plays a key role to ensure the consistency of the MLE.

Invertibility



■ The filtered parameter $\{\hat{f}_t(\theta)\}_{t\in\mathbb{N}}$ at θ is invertible if

$$\left|\hat{f}_t(\theta) - \tilde{f}_t(\theta)
ight| \xrightarrow{a.s.} 0, \quad \text{ as } t o \infty.$$

for any $\hat{f}_1(\theta) \in \mathcal{F}$, where $\{\tilde{f}_t(\theta)\}_{t \in \mathbb{Z}}$ is a stochastic sequence.

■ Invertibility guarantees that the path of the true time varying parameter f_t^o can be recovered asymptotically, i.e. $|\hat{f}_t(\theta_0) - f_t^o| \xrightarrow{a.s.} 0$.

Invertibility is not merely a technical condition, see Sorokin (2011) and Wintenberger (2013).

Why is invertibility important?



EGARCH(1,1):
$$y_t = \exp(f_t/2)\varepsilon_t$$
, $f_{t+1} = \omega + \beta f_t + \alpha |\varepsilon_t|$.

- $|\beta_0|$ < 1 ensures stationarity of the EGARCH(1,1) process.
- $|\beta_0| < 1$ does not ensure invertibility of the filter $\hat{f}_t(\theta_0)$.

Plot of $10^{-5} \sum_{t=1}^{10^5} |f_t^o - \hat{f}_t(\theta_0)|$ for different initializations $\hat{f}_1(\theta_0)$.

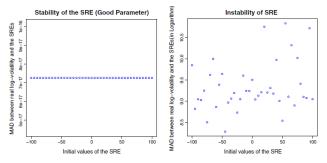


Figure: Non-invertibility example of EGARCH(1,1) from Wintenberger (2013).

How can we ensure invertibility?



- As in Straumann and Mikosh (2006), sufficient conditions for invertibility can be obtained on the basis of Theorem 3.1 of Bougerol (1993).
- Bougerol's theorem provides general conditions for stability of stochastic processes.
- lacktriangle We obtain that $\{\hat{f}_t(\theta)\}_{t\in\mathbb{N}}$ is invertible if

$$E\log\Lambda_t(\theta)<0,$$

where

$$\Lambda_t(\theta) = \sup_{f} \left| \frac{\partial \phi(f, y_t, \theta)}{\partial f} \right|.$$

Invertibility: GARCH and EGARCH



■ GARCH(1,1) model

Filtered parameter:

$$\hat{f}_{t+1}(\theta) = \omega + \beta \hat{f}_t(\theta) + \alpha y_t^2$$

Invertibility condition:

$$E \log \sup_{f} |\partial (\beta f + \alpha y_t^2)/\partial f| = \log(\beta) < 0.$$

■ EGARCH(1,1) model

Filtered parameter:

$$\hat{f}_{t+1}(\theta) = \omega + \beta \hat{f}_t(\theta) + \alpha |y_t| \exp\left(-\hat{f}_t(\theta)/2\right).$$

Invertibility condition:

$$E \log \sup_{f} |\partial (\beta f + \alpha | y_t | \exp(-f/2)) / \partial f| =$$

$$E \log \max \left\{ \beta, 2^{-1}\alpha |y_t| \exp(-2^{-1}\omega/(1-\beta)) - \beta \right\} < 0.$$

Invertibility in practice



- Often, in practice, $E \log \Lambda_t(\theta) < 0$ cannot be checked directly as $\Lambda_t(\theta)$ depends on the unknown data generating process.
- This leads to either a very small region or a degenerate region Θ where the likelihood should maximized

$$\hat{\theta}_n = \underset{\theta \in \Theta}{\operatorname{arg\,max}} \hat{L}_n(\theta),$$

■ In practical applications, invertibility conditions are ignored and therefore the **consistency of the MLE** is **not guaranteed** and it may not be possible to uncover the true path f_t^o .

MLE on an empirical region



■ To handle this issue we define the MLE on a parameter region that satisfies an **empirical** version of the **invertibility condition** $E \log \Lambda_t(\theta) < 0$, namely

$$\tilde{\theta}_n = \arg\max_{\theta \in \hat{\Theta}_n} \hat{L}_n(\theta),$$

where

$$\hat{\Theta}_n = \left\{ \theta \in \bar{\Theta} : \frac{1}{n} \sum_{t=1}^n \log \Lambda_t(\theta) < 0 \right\}.$$

■ Wintenberger (2013) first proposed the estimation of the parameter region for the QMLE of the EGARCH(1,1) model.

Consistency of the MLE



We consider the following conditions:

- (C.1) The data generating process is stationary with $E \log \Lambda_t(\theta_0) < 0$.
- (C.2) The model is identifiable.
- (C.3) The $\log \Lambda_t(\theta)$ is a.s. continuous and it has a finite first moment.
- (C.4) The log-likelihood function is Lipschitz continuous with respect to $\hat{f}_t(\theta)$.
- (C.5) The first moment of the likelihood function is uniformly bounded.

Theorem

Let conditions (C.1)-(C.5) hold, then the MLE $\tilde{\theta}_n$ is strongly consistent, i.e.

$$\tilde{\theta}_n \xrightarrow{a.s.} \theta_0, \qquad n \to \infty.$$

Furthermore, $|\hat{f}_n(\tilde{\theta}_n) - f_n^o| \xrightarrow{a.s.} 0$ as n goes to infinity.

Example 1: the model



■ The **Beta-t-GARCH model** with leverage effects of Creal et al. (2013) and Harvey (2013) is

$$y_t = \sqrt{f_t} \varepsilon_t, \quad \varepsilon_t \sim t_v(0,1),$$

$$f_{t+1} = \omega + \beta f_t + (\alpha + \gamma d_t) \frac{(v+1)y_t^2}{(v-2) + f_t^{-1}y_t^2},$$

where $d_t = 1$ if $y_t \le 0$ and $d_t = 0$ otherwise.

■ The invertibility condition $E \log \Lambda_t(\theta) < 0$ is given by

$$E \log \left| \beta + (\alpha + \gamma d_t) \frac{(\nu + 1)y_t^4}{((\nu - 2)\bar{\omega} + y_t^2)^2} \right| < 0, \quad \forall \ \theta \in \Theta.$$

Example 1: the parameter region



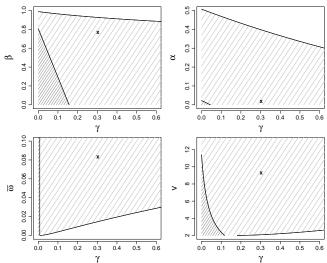


Figure: Invertibility regions obtained considering the monthly log-differences of the S&P 500 stock index.

Example 2: the model



■ The **dynamic autoregressive model** Blasques et al. (2014) and Delle Monache and Petrella (2014) is

$$y_{t} = f_{t}y_{t-1} + \sigma\varepsilon_{t}, \quad \varepsilon_{t} \sim t_{v},$$

$$f_{t+1} = \omega + \beta f_{t} + \alpha \frac{(y_{t} - f_{t}y_{t-1})y_{t-1}}{1 + v^{-1}\sigma^{-2}(y_{t} - f_{t}y_{t-1})^{2}},$$

■ The invertibility condition $E \log \Lambda_t(\theta) < 0$ is given by

$$E\log\max\left\{\left|\beta-\alpha y_t^2\right|,\left|\beta+\frac{\alpha}{8}y_t^2\right|\right\}<0,\quad\forall\;\theta\in\Theta.$$

■ Sufficient conditions leads to a degenerate region with $\alpha = 0$.

Example 2: the parameter region



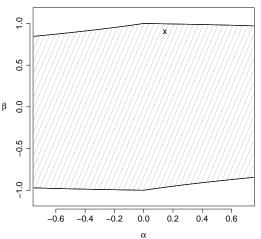


Figure: Invertibility region obtained considering the monthly log-differences of the US unemployment claims.

Concluding remarks



- Even if θ_0 does not satisfy $E \log \Lambda_0(\theta_0) < 0$, the MLE $\tilde{\theta}_n$ and the filtered parameter $\hat{f}_n(\tilde{\theta}_n)$ asymptotically does not depend on the initialization $\hat{f}_1(\theta)$.
- In the case of model misspecification, the MLE $\tilde{\theta}_n$ is consistent w.r.t. a pseudo true parameter θ^* . This pseudo true parameter has the interpretation of being the minimizer of the following marginal KL divergence

$$KL(\theta) = E \log p^{o}(y_t|y^{t-1}) - E \log p(y_t|f_t(\theta), \theta),$$

where $p^{o}(y_{t}|y^{t-1})$ denotes the unknown true conditional distribution of y_{t} .

Main references



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